

Lagrange's Interpolating Polynomial for Approximating The Derivatives and The Calculation of The Electric Field and Charge from The Potential

Function

11/11/2012

Viewgraphs are Copyright © Dr. Atef Elsherbeni

1

Lagrange's Interpolating Polynomial for Approximating the Derivatives

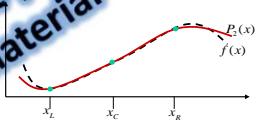
Three consecutive nodes with arbitrary separation



Lagrange's Interpolating polynomial is described as

$$P_2(x) = \frac{(x - x_C)(x - x_R)}{(x_L - x_C)(x_L - x_R)} f(x_L) + \frac{(x - x_L)(x - x_R)}{(x_C - x_L)(x_C - x_R)} f(x_C) + \frac{(x - x_L)(x - x_C)}{(x_R - x_L)(x_R - x_C)} f(x_R)$$

$P_2(x)$ is a second degree polynomial which coincides with the exact values of the function $f(x)$ at three nodes L, R, C and approximates the function $f(x)$ in between these nodes.



11/11/2012

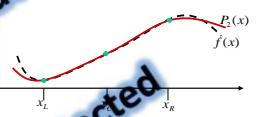
Viewgraphs are Copyright © Dr. Atef Elsherbeni

2

Derivatives of Lagrange's Interpolating Polynomial

Lagrange's interpolating polynomial is differentiated to obtain approximations for the first and second derivatives of a function $f(x)$ based on known numerical values at three points of the function.

In our case the left, center, and right values are sufficient to determine the first and second derivatives of a potential V in x direction at any point x between the left and right positions x_L and x_R .



$$\frac{df}{dx} = \frac{(x - x_C) + (x - x_R)}{(x_L - x_C)(x_L - x_R)} f(x_L) + \frac{(x - x_L) + (x - x_R)}{(x_C - x_L)(x_C - x_R)} f(x_C) + \frac{(x - x_L) + (x - x_C)}{(x_R - x_L)(x_R - x_C)} f(x_R)$$

$$\frac{d^2 f}{dx^2} = \frac{2f(x_L) - 2f(x_C) - 2f(x_R)}{(x_L - x_C)(x_L - x_R)(x_C - x_R)}$$

Similar expressions can be obtained for the y derivatives.

3

11/11/2012

Viewgraphs are Copyright © Dr. Atef Elsherbeni

1

Quantities Computed From The Potential

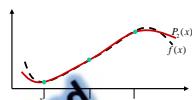
- The electric field vectors $\vec{E} = -\nabla V$
- The charge on a conductor (Gauss's Law)
- The capacitance between conductors
- The characteristic impedance, effective dielectric constant, phase velocity.

Electric Field Distribution

After solving for the potential distribution, the electric field vector can be calculated at every node

$$\vec{E}(x, y) = -\nabla V(x, y) = -\frac{\partial V(x, y)}{\partial x} \hat{x} - \frac{\partial V(x, y)}{\partial y} \hat{y}$$

$$\vec{E}_x = E_x(x, y) \hat{x} + E_y(x, y) \hat{y}$$



Since we are using a non-uniform grid, the potential can best be described at any arbitrary point using Lagrange's polynomials approximation

$$V(x, y) \approx P_2(x, y) = \frac{(x - x_c)(x - x_g)}{(x_c - x_c)(x_c - x_g)} V(x_c, y) + \frac{(x - x_c)(x - x_r)}{(x_c - x_c)(x_c - x_r)} V(x_r, y) + \frac{(x - x_g)(x - x_c)}{(x_g - x_c)(x_g - x_c)} V(x_g, y)$$

$$\frac{dV(x, y)}{dx} = \frac{2x - x_c - x_g}{(x_c - x_c)(x_c - x_g)} V(x_c, y) + \frac{2x - x_c - x_r}{(x_c - x_c)(x_c - x_r)} V(x_r, y) + \frac{2x - x_g - x_c}{(x_g - x_c)(x_g - x_c)} V(x_g, y)$$

$$E_x(x, y) = -\frac{2x - x_c - x_g}{(x_c - x_c)(x_c - x_g)} V_c|_c - \frac{2x - x_c - x_g}{(x_c - x_c)(x_c - x_g)} V_c|_r - \frac{2x - x_c - x_g}{(x_g - x_c)(x_g - x_c)} V_g|_g$$

$$E_y(x, y) = -\frac{2y - y_c - y_g}{(y_c - y_c)(y_c - y_g)} V_g|_g - \frac{2y - y_c - y_r}{(y_c - y_c)(y_c - y_r)} V_c|_r - \frac{2y - y_g - y_c}{(y_g - y_c)(y_g - y_c)} V_r|_r$$

Electric Field Vectors

$$E_x(x, y) = -\frac{2x - x_c - x_g}{(x_c - x_c)(x_c - x_g)} V_l|_y - \frac{2x - x_l - x_g}{(x_c - x_l)(x_c - x_g)} V_c|_y - \frac{2x - x_g - x_c}{(x_g - x_c)(x_g - x_c)} V_r|_y$$

$$E_y(x, y) = -\frac{2y - y_c - y_g}{(y_c - y_c)(y_c - y_g)} V_g|_x - \frac{2y - y_g - y_c}{(y_g - y_c)(y_g - y_c)} V_c|_x - \frac{2y - y_g - y_c}{(y_c - y_c)(y_c - y_c)} V_r|_x$$

Thus in terms of the potential $V(i, j)$ and the coordinates $x(i, j)$ and $y(i, j)$ using the following definitions:

$$V_c = V_{(i,j)}, V_T = V_{(i,j+1)}, V_B = V_{(i,j-1)}, V_R = V_{(i+1,j)}, V_L = V_{(i-1,j)}$$

$$x_c = x(i, j), x_T = x(i, j+1), x_B = x(i, j-1), x_R = x(i+1, j), x_L = x(i-1, j)$$

$$y_c = y(i, j), y_T = y(i, j+1), y_B = y(i, j-1), y_R = y(i+1, j), y_L = y(i-1, j)$$

One can obtain the components of the electric field $E_x(x, y)$ and $E_y(x, y)$ at any arbitrary point (x, y) in the computational domain.

Electric Field Components at the Grid Points

$$E_x(x, y) = -\frac{2x - x_c - x_g}{(x_c - x_g)(x_c - x_g)} V_L |_x - \frac{2x - x_g - x_c}{(x_c - x_g)(x_c - x_g)} V_C |_y - \frac{2x - x_g - x_c}{(x_g - x_c)(x_g - x_c)} V_R |_y$$

$$E_y(x, y) = -\frac{2y - y_c - y_g}{(y_g - y_c)(y_g - y_c)} V_L |_x - \frac{2y - y_g - y_c}{(y_c - y_g)(y_c - y_g)} V_C |_x - \frac{2y - y_g - y_c}{(y_g - y_c)(y_g - y_c)} V_R |_x$$

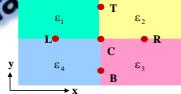
At $x = x_c, y = y_c$

$$E_x(x_c, y_c) = -\frac{x_c - x_g}{(x_c - x_g)(x_c - x_g)} V_L |_{y_c} - \frac{(x_c - x_g) + (x_c - x_g)}{(x_c - x_g)(x_c - x_g)} V_C |_{y_c} - \frac{x_c - x_g}{(x_g - x_c)(x_g - x_c)} V_R |_{y_c}$$

$$E_y(x_c, y_c) = -\frac{y_c - y_g}{(y_g - y_c)(y_g - y_c)} V_L |_{x_c} - \frac{(y_c - y_g) + (y_c - y_g)}{(y_c - y_g)(y_c - y_g)} V_C |_{x_c} - \frac{y_c - y_g}{(y_g - y_c)(y_g - y_c)} V_R |_{x_c}$$

For $\Delta x = \Delta y = h$

$$E_x(x_c, y_c) = \frac{V_L}{2h} - \frac{V_R}{2h}, \quad E_y(x_c, y_c) = \frac{V_L}{2h} - \frac{V_R}{2h}$$



11/11/2012

Viewgraphs are Copyright © Dr. Atef Elsherbeni

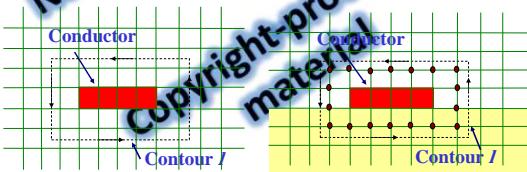
7

Computation of the Total Charge on a Conductor

$$Q^{enc} = -\oint_A \epsilon \frac{\partial V}{\partial n} \hat{a}_n \cdot d\vec{A} = \oint_A \epsilon \frac{\partial V}{\partial n} dA$$



$$\rho^{enc} = -\oint_l \epsilon \frac{\partial V}{\partial n} dl$$



11/11/2012

Viewgraphs are Copyright © Dr. Atef Elsherbeni

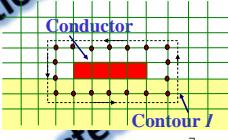
8

Computation of The Total Charge on a Conductor

Gauss's Law

$$Q^{enc} = -\oint_A \epsilon \frac{\partial V}{\partial n} \hat{a}_n \cdot d\vec{A} = -\oint_A \epsilon \frac{\partial V}{\partial n} dA$$

$$\rho^{enc} = -\oint_l \epsilon \frac{\partial V}{\partial n} dl \quad \text{Charge enclosed per unit length}$$



$$\rho^{enc} = \left[\int_{right} \epsilon(y) \frac{\partial V}{\partial x} dy - \int_{top} \epsilon(x) \frac{\partial V}{\partial y} dx + \int_{left} \epsilon(y) \frac{\partial V}{\partial x} dy + \int_{bottom} \epsilon(x) \frac{\partial V}{\partial y} dx \right]$$

$$\text{with the approximations } \frac{\partial V}{\partial x} \approx \frac{V_R - V_C}{x_R - x_C} \text{ and } \frac{\partial V}{\partial y} \approx \frac{V_T - V_C}{y_T - y_C}$$

$$\rho^{enc} = -\sum_{right} \frac{V_R - V_C}{x_R - x_C} \left[\frac{\epsilon_1(y_C - y_T) + \epsilon_2(y_T - y_C)}{2} \right] dx + \sum_{top} \frac{V_T - V_C}{y_T - y_C} \left[\frac{\epsilon_1(x_C - x_R) + \epsilon_2(x_R - x_C)}{2} \right] dx + \sum_{left} \frac{V_C - V_L}{x_C - x_L} \left[\frac{\epsilon_3(y_T - y_C) + \epsilon_4(y_C - y_T)}{2} \right] dy + \sum_{bottom} \frac{V_C - V_B}{y_C - y_B} \left[\frac{\epsilon_3(x_C - x_R) + \epsilon_4(x_R - x_C)}{2} \right] dx$$

11/11/2012

Viewgraphs are Copyright © Dr. Atef Elsherbeni

9

Computation of The Total Charge on a Conductor

And by using coordinates indices (i, j) :

$$\rho^{enc} = -\sum_{right} \frac{V_R - V_C}{x_R - x_C} \left[\frac{\varepsilon_1(y_C - y_B) + \varepsilon_2(y_T - y_C)}{2} \right] - \sum_{top} \frac{V_T - V_C}{y_T - y_C} \left[\frac{\varepsilon_1(x_C - x_L) + \varepsilon_2(x_B - x_C)}{2} \right]$$

$$+ \sum_{left} \frac{V_C - V_L}{x_C - x_L} \left[\frac{\varepsilon_1(y_T - y_B) + \varepsilon_2(x_B - x_L)}{2} \right] + \sum_{bottom} \frac{V_C - V_B}{y_C - y_B} \left[\frac{\varepsilon_1(x_C - x_L) + \varepsilon_2(x_B - x_C)}{2} \right]$$

$$\rho^{enc} = -\sum_{right} \frac{V_{(i+1,j)} - V_{(i,j)}}{x(i+1,j) - x(i,j)} \left[\frac{\varepsilon_{(i,j)}(y(i,j) - y(i,j-1)) + \varepsilon_{(i+1,j)}(y(i+1,j) - y(i,j))}{2} \right]$$

$$- \sum_{top} \frac{V_{(i,j+1)} - V_{(i,j)}}{y(i,j+1) - y(i,j)} \left[\frac{\varepsilon_{(i-1,j)}(x(i,j) - x(i-1,j)) + \varepsilon_{(i,j)}(x(i,j+1) - x(i,j))}{2} \right]$$

$$+ \sum_{left} \frac{V_{(i,j)} - V_{(i-1,j)}}{x(i,j) - x(i-1,j)} \left[\frac{\varepsilon_{(i-1,j)}(x(i,j) - x(i-1,j)) + \varepsilon_{(i,j)}(x(i,j+1) - x(i,j-1))}{2} \right]$$

$$+ \sum_{bottom} \frac{V_{(i,j)} - V_{(i,j-1)}}{y(i,j) - y(i,j-1)} \left[\frac{\varepsilon_{(i-1,j-1)}(x(i,j) - x(i-1,j)) + \varepsilon_{(i,j)}(x(i+1,j) - x(i,j))}{2} \right]$$

11/11/2012

Viewgraphs are Copyright © Dr. Atef Elsherbeni

10

Computation of The Total Charge on a Conductor

For $\Delta x = \Delta y = h$

$$\rho^{enc} = \left[- \int_{right} \varepsilon(y) \frac{\partial V}{\partial x} dy - \int_{top} \varepsilon(x) \frac{\partial V}{\partial y} dx + \int_{left} \varepsilon(y) \frac{\partial V}{\partial x} dy + \int_{bottom} \varepsilon(x) \frac{\partial V}{\partial y} dx \right]$$

$$\rho^{enc} = -\sum_{right} (V_R - V_C) \left[\frac{\varepsilon_1 + \varepsilon_2}{2} \right] - \sum_{top} (V_T - V_C) \left[\frac{\varepsilon_1 + \varepsilon_2}{2} \right]$$

$$+ \sum_{left} (V_C - V_L) \left[\frac{\varepsilon_1 + \varepsilon_2}{2} \right] + \sum_{bottom} (V_C - V_B) \left[\frac{\varepsilon_1 + \varepsilon_2}{2} \right]$$

$$\rho^{enc} = -\sum_{right} (V_{(i+1,j)} - V_{(i,j)}) \left[\frac{\varepsilon_{(i,j)} + \varepsilon_{(i+1,j)}}{2} \right] - \sum_{top} (V_{(i,j+1)} - V_{(i,j)}) \left[\frac{\varepsilon_{(i-1,j)} + \varepsilon_{(i,j)}}{2} \right]$$

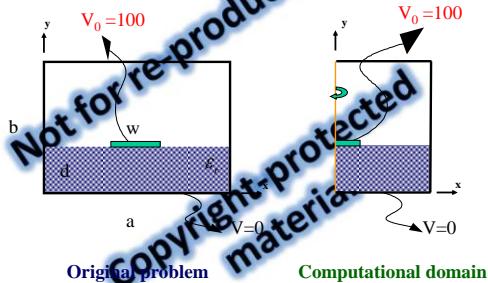
$$+ \sum_{left} (V_{(i,j)} - V_{(i-1,j)}) \left[\frac{\varepsilon_{(i-1,j)} + \varepsilon_{(i,j)}}{2} \right] + \sum_{bottom} (V_{(i,j)} - V_{(i,j-1)}) \left[\frac{\varepsilon_{(i-1,j-1)} + \varepsilon_{(i,j)}}{2} \right]$$

11/11/2012

Viewgraphs are Copyright © Dr. Atef Elsherbeni

11

A Shielded Microstrip Line Geometry



11/11/2012

Viewgraphs are Copyright © Dr. Atef Elsherbeni

12

Parameters of a Microstrip Line

Capacitance

$$C = \frac{\rho^{enc}}{V}$$

Phase velocity

$$v = \frac{c}{\sqrt{\epsilon_r}}, c \approx 3 \times 10^8$$

Effective permittivity

$$\epsilon_{eff} = \frac{\rho^{enc}}{\rho_0^{enc}}, \quad \rho_0^{enc} \text{ is the charge with } \epsilon_r = 1$$

Characteristic impedance

$$Z_0 = \frac{1}{c\sqrt{C\epsilon_r}} \approx 3 \times 10^8, C \text{ is the capacitance with } \epsilon_r = 1$$

Assignment

For the shown cross-section of a shielded microstrip transmission line that extends along the x axis. Assuming that there is no variation along the x direction, calculate the following parameters of the microstrip line using the FD technique. (i) central difference approximation, matrix inversion solution.

a) 3D graphs of potential distribution for $\epsilon_r = 1$

b) 2D graphs of electric field distribution for $\epsilon_r = 1$, and $\epsilon_r = 12$

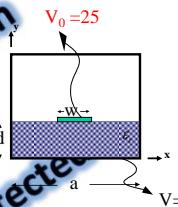
c) total charge on the strip for $\epsilon_r = 1$, and $\epsilon_r = 12$

d) strip capacitance for $\epsilon_r = 1$, and $\epsilon_r = 12$

e) strip characteristic impedance

f) strip effective permittivity

g) strip phase velocity.



The computations of the potential using the FD technique must be performed over one half of the cross-section of the geometry.

Matlab functions to generate the complete potential distribution for the complete cross-section before computing the electric field, charge, etc.

$a = 7.5, b = 5.5, d = 1.5, w = 1.5, \epsilon_r = 12$

Thickness of the strip = 0.05

All dimensions are in cm.

Bonus points:

1- compute and sketch the charge distribution on the top surface of the strip.

2- use Lagrange's interpolation for the evaluation of the derivatives of the potential in the integrant part of Gauss's law.

End of Lecture